

# MTM3502-Partial Differential Equations

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Week 10



## Second Order Linear PDEs: Canonical Forms of Hyperbolic PDEs

The general solutions of hyperbolic PDEs are obtained by their canonical forms. However, sometimes, it might not be so simple to determine the general solution of a given equation. If the canonical form of the equation is simple, then the general solution can be immediately ascertained. Let us recall the example of last week.

### Example 18

*Consider the PDE*

$$y^2 u_{xx} - x^2 u_{yy} = 0. \quad (5.18)$$

The canonical form of the given equation was

$$u_{\xi\eta} = \frac{\eta}{2(\xi^2 - \eta^2)} u_{\xi} - \frac{\xi}{2(\xi^2 - \eta^2)} u_{\eta}. \quad (5.21)$$

where  $\xi = y^2 - x^2$  and  $\eta = y^2 + x^2$ .

## Second Order Linear PDEs: Canonical Forms of Hyperbolic PDEs

Multiplying both sides with  $-4$ , we obtain

$$\begin{aligned} -4u_{\xi\eta} &= \frac{2\eta}{\eta^2 - \xi^2} u_{\xi} - \frac{2\xi}{\eta^2 - \xi^2} u_{\eta} \\ \implies -4u_{\xi\eta} &= \left( \ln(\eta^2 - \xi^2) \right)_{\eta} u_{\xi} + \left( \ln(\eta^2 - \xi^2) \right)_{\xi} u_{\eta}. \end{aligned} \quad (6.1)$$

Without loss of generality, let us choose

$$-2u_{\xi\eta} = \left( \ln(\eta^2 - \xi^2) \right)_{\eta} u_{\xi}, \quad (u_1 = u_{\xi}), \quad (6.2a)$$

$$-2u_{\xi\eta} = \left( \ln(\eta^2 - \xi^2) \right)_{\xi} u_{\eta}, \quad (u_2 = u_{\eta}), \quad (6.2b)$$

## Second Order Linear PDEs: Canonical Forms of Hyperbolic PDEs

From (6.2a), we have

$$\begin{aligned}\frac{du_1}{u_1} &= -\frac{(\ln(\eta^2 - \xi^2))_\eta}{2} d\eta \\ \Rightarrow \ln u_1 &= -\frac{\ln(\eta^2 - \xi^2)}{2} + \ln \varphi(\xi) \\ \Rightarrow u_1 = u_\eta &= \frac{\varphi(\xi)}{\sqrt{\eta^2 - \xi^2}} \\ \Rightarrow u &= \varphi(\xi) \tanh^{-1} \left( \frac{\eta}{\sqrt{\eta^2 - \xi^2}} \right) + \varphi_1(\xi)\end{aligned}\tag{6.3}$$

Similarly, from (6.2b), we have

$$\begin{aligned}u_2 = u_\xi &= \frac{\phi(\eta)}{\sqrt{\eta^2 - \xi^2}} \\ \Rightarrow u &= \phi(\eta) \tan^{-1} \left( \frac{\xi}{\sqrt{\eta^2 - \xi^2}} \right) + \phi_1(\eta)\end{aligned}\tag{6.4}$$

## Second Order Linear PDEs: Canonical Forms of Hyperbolic PDEs

Solving (6.3) and (6.4) together, we obtain

$$\begin{aligned} u(\xi, \eta) &= c_1 \tanh^{-1} \left( \frac{\eta}{\sqrt{\eta^2 - \xi^2}} \right) \tanh^{-1} \left( \frac{\xi}{\sqrt{\eta^2 - \xi^2}} \right) + c_2 \\ \implies u(x, y) &= c_1 \tanh^{-1} \left( \frac{y^2 + x^2}{2xy} \right) \tanh^{-1} \left( \frac{y^2 - x^2}{2xy} \right) + c_2 \end{aligned} \quad (6.5)$$

which is a solution to (5.18) where  $c_1$  and  $c_2$  are arbitrary constants.

## SO Linear PDEs with Constant Coefficients and Operator Factorization

The general form of a second order linear PDE was given as

$$Au_{xx} + Bu_{xy} + Cu_{yy} + Du_x + Eu_y + Fu = G. \quad (5.1)$$

If  $A, B, C, D, E$  and  $F$  are real constants and  $G$  is a continuous function of  $x$  and  $y$ , then (5.1) is called a second order linear PDE with constant coefficients. This week, we will consider PDEs of these particular type and present an operator factorization technique for these type of PDEs.

In order to restate (5.1) in operator form, we define the following partial differential operators

$$\begin{aligned} D_x &= \frac{\partial}{\partial x}, D_y = \frac{\partial}{\partial y}, \\ D_x^2 &= \frac{\partial^2}{\partial x^2}, D_y^2 = \frac{\partial^2}{\partial y^2}, D_x D_y = \frac{\partial^2}{\partial x \partial y}. \end{aligned} \quad (7.1)$$

## SO Linear PDEs with Constant Coefficients and Operator Factorization

Then, (5.1) will be restated as

$$Lu = G(x, y) \quad (7.2)$$

where

$$L = AD_x^2 + BD_xD_y + CD_y^2 + DD_x + ED_y + F \quad (7.3)$$

is the partial differential operator for (5.1). The operator  $L$  is a linear operator which satisfy the following property, for real constants  $c_1$  and  $c_2$  and partially second order differentiable functions  $u_1$  and  $u_2$ ,

$$L(c_1u_1 + c_2u_2) = c_1Lu_1 + c_2Lu_2. \quad (7.3)$$

Suppose that  $u_1$  and  $u_2$  are the solutions to the homogeneous PDE

$$Lu = 0 \implies Lu_1 = 0 \text{ and } Lu_2 = 0. \quad (7.4)$$

## SO Linear PDEs with Constant Coefficients and Operator Factorization

Then, from linearity of  $L$ , the linear combination of  $u_1$  and  $u_2$ , which is  $c_1 u_1 + c_2 u_2$  for nonzero reals  $c_1$  and  $c_2$ , is also a solution of (7.4). This property is called as the *superposition principle*. The general solution of (7.4) is called the *homogeneous solution* and denoted as  $u_h$  whereas the particular solution to (7.2) is called the *particular solution* and denoted as  $u_p$ . Thus, the general solution of (7.2) have the following form

$$u = u_h + u_p. \quad (7.5)$$

Suppose that the operator  $L$  can be factorized as

$$L = L_1 L_2 = (\alpha_1 D_x + \beta_1 D_y + \gamma_1)(\alpha_2 D_x + \beta_2 D_y + \gamma_2) \quad (7.6)$$

where  $\alpha_i, \beta_i, \gamma_i \in \mathbb{R}$ , for  $i = 1, 2$ . If  $u = u(x, t)$  is a solution of  $L_2 u = 0$ , then  $Lu = L_1 L_2 u = L_1 \cdot 0 = 0$  so that it is also a solution for  $Lu = 0$  (the same can also shown for  $L_1 u = 0$ , without loss of generality). Now, let us consider

$$L_1 u = (\alpha_1 D_x + \beta_1 D_y + \gamma_1)u = \alpha_1 p + \beta_1 q + \gamma_1 u = 0. \quad (7.7)$$



## SO Linear PDEs with Constant Coefficients and Operator Factorization

From the Lagrange auxiliary equation, we have

$$\frac{dx}{\alpha_1} = \frac{dy}{\beta_1} = \frac{du}{-\gamma_1 u}. \quad (7.8)$$

Now, we consider three cases:

- Suppose  $\alpha_1 \neq 0$  holds. From (7.8), we have

$$\begin{aligned} \frac{dx}{\alpha_1} = \frac{dy}{\beta_1} &\implies \beta_1 x - \alpha_1 y = c_1 \\ -\frac{\gamma_1}{\alpha_1} dx = \frac{du}{u} &\implies u = c_2 e^{-\frac{\gamma_1}{\alpha_1} x}. \end{aligned} \quad (7.9)$$

Therefore, the general solution of (7.7) will be

$$u_{h1} = e^{-\frac{\gamma_1}{\alpha_1} x} \varphi(\beta_1 x - \alpha_1 y), \quad (7.10)$$

where  $\varphi$  is an arbitrary function.

## SO Linear PDEs with Constant Coefficients and Operator Factorization

From the Lagrange auxiliary equation, we have

$$\frac{dx}{\alpha_1} = \frac{dy}{\beta_1} = \frac{du}{-\gamma_1 u}. \quad (7.8)$$

Now, we consider three cases:

- Suppose  $\beta_1 \neq 0$  holds. From (7.8), the general solution of (7.7) will be

$$u_{h1} = e^{-\frac{\gamma_1}{\beta_1}y} \tilde{\varphi}(\beta_1 x - \alpha_1 y), \quad (7.11)$$

where  $\tilde{\varphi}$  is an arbitrary function.

- In the general case that both  $\alpha_1 \neq 0$  and  $\beta_1 \neq 0$  hold, either (7.10) or (7.11) may be chosen for general solution.

## SO Linear PDEs with Constant Coefficients and Operator Factorization

Similarly, the general solution of

$$\begin{aligned}L_2 u &= (\alpha_2 D_x + \beta_2 D_y + \gamma_2) u \\ &= \alpha_2 p + \beta_2 q + \gamma_2 u = 0\end{aligned}\tag{7.12}$$

will be either

$$u_{h2} = e^{-\frac{\gamma_2}{\alpha_2} x} \phi(\beta_2 x - \alpha_2 y),\tag{7.13}$$

for  $\alpha_2 \neq 0$  or

$$u_{h2} = e^{-\frac{\gamma_2}{\beta_2} y} \tilde{\phi}(\beta_2 x - \alpha_2 y),\tag{7.14}$$

for  $\beta_2 \neq 0$ . As a result, the general homogeneous solution of  $Lu = 0$  will be

$$\begin{aligned}u_h &= u_{h1} + u_{h2} \\ &= e^{-\frac{\gamma_1}{\alpha_1} x} \varphi(\beta_1 x - \alpha_1 y) + e^{-\frac{\gamma_2}{\alpha_2} x} \phi(\beta_2 x - \alpha_2 y).\end{aligned}\tag{7.15}$$

## SO Linear PDEs with Constant Coefficients and Operator Factorization

In the case that  $\alpha_1 = \alpha_2 = \alpha$  and  $\beta_1 = \beta_2 = \beta$ , the homogeneous solutions of  $Lu = 0$  will be

$$u_h = e^{-\frac{\gamma}{\alpha}x} (x\varphi(\beta x - \alpha y) + \phi(\beta x - \alpha y)). \quad (7.16)$$

for  $\alpha \neq 0$  and

$$u_h = e^{-\frac{\gamma}{\beta}y} (y\varphi(\beta x - \alpha y) + \phi(\beta x - \alpha y)). \quad (7.17)$$

for  $\beta \neq 0$ .

## SO Linear PDEs with Constant Coefficients and Operator Factorization

The particular solution requires that we make an “initial assumption” about the form of the particular solution  $u_p(x, y)$ , but with the coefficients left unspecified. For the particular solution, the type of  $G(x, y)$  in (7.2) determines the types of the particular solution candidate. Here are some of the following particular solution candidates for various types.

**Table:** Particular Solution Candidates for Various Types of  $G(x, y)$ .

$G(x, y)$	Particular Solution Candidate $u_p(x, y)$
Trigonometric	Trigonometric
Polynomial	Polynomial
Exponential	Exponential

## SO Linear PDEs with Constant Coefficients and Operator Factorization

### Example 21

*Find the homogeneous and particular solution of*

$$u_{xx} - u_{yy} - u_x + u_y = 2 \cos(3x + 2y). \quad (7.18)$$

## SO Linear PDEs with Constant Coefficients and Operator Factorization

### Example 22

*Find the general solution of*

$$4u_{xx} - 4u_{xy} + u_{yy} + 4u_x - 2u_y = 0. \quad (7.29)$$

## SO Linear PDEs with Constant Coefficients and Operator Factorization

### Example 23

*Find the general solution of*

$$(2D_x^2 - 5D_x D_y + 2D_y^2)u = 5e^{x+3y}. \quad (7.32)$$

*where  $D_x^2$ ,  $D_x D_y$  and  $D_y^2$  are defined as in (7.1)*