# MTM4501-Operations Research

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Week 2

MTM4501

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# **Course Content**

- Definition of OR and Its History
- Decision Theory and Models
  - Decision Making Under Certainty
  - Decision Making Under Risk
  - Decision Making Under Uncertainty
- Network Analysis
- Inventory Management Models
- Queue Models

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# **Decision Theory: Basic Concepts**

Components of the Decision Making Problem:

- Decision Maker (Person-Group)
- Objective/Decision Criteria
- Actions/Strategies/Alternatives (a<sub>i</sub>, i = 1, 2, ..., m)
- States (*s<sub>j</sub>*, *j* = 1, 2, ..., *n*)

■ Results v(a<sub>i</sub>, s<sub>j</sub>): The value resulting from each option and event. In other words, when a<sub>i</sub> action is selected, if s<sub>j</sub> state is encountered, v(a<sub>i</sub>, s<sub>j</sub>) result is obtained. In mathematical terms v<sub>ij</sub> = v(a<sub>i</sub>, s<sub>j</sub>); that is, v(·, ·) is a function of the variables a<sub>i</sub> and s<sub>j</sub>.

Payoff Matrix (Decision Matrix):

|       | <i>S</i> <sub>1</sub>   | <b>s</b> <sub>2</sub>                                      |   | <b>S</b> j    |   | Sn            |
|-------|---|--|---|---------------|---|---------------|
| $a_1$ |   | <i>v</i> ( <i>a</i> <sub>1</sub> , <i>s</i> <sub>2</sub> ) |   | $v(a_1, s_j)$ |   | $v(a_1, s_n)$ |
| $a_2$ | $v(a_2, s_1)$   | $v(a_2, s_2)$  |   | $v(a_2, s_j)$ |   | $v(a_2, s_n)$ |
| ÷     | :   | :  | · | ÷             | · | ÷             |
| $a_i$ | :<br><i>v</i> ( <i>a</i> <sub>i</sub> , <i>s</i> <sub>1</sub> ) | $v(a_i, s_2)$  |   | $v(a_i, s_j)$ |   | $v(a_i, s_n)$ |
| ÷     | :   |  | · |               | · | :             |
| $a_m$ | $v(a_m, s_1)$   | $v(a_m, s_2)$  |   | $v(a_m, s_j)$ |   | $v(a_m, s_n)$ |
|       |   |  |   |               |   |               |

#### Example

A wholesaler is considering to order apples at the beginning of the week. Apples are bought in 100 kg boxes and sold to greengrocers. The purchasing price of apples is 6 TL/kg, and the selling price to greengrocers is 10 TL/kg. At the end of the week, the wholesaler transfers the remaining apples to marketers at a price of 4 TL/kg. From this wholesaler's experience from the previous weeks; he/she knows that the demand for a box of apples is at least 0 and at most 4 boxes. How many boxes of apples should this wholesaler order?

- $0 \le a_i \le 4$ : action  $a_i$  represents ordering *i* boxes of apples,
- $0 \le s_j \le 4$ : state  $s_i$  represents demanding *i* boxes of apples,
- Purchasing price of a box:
- Sale price of a box to greengrocers:
- Sale price of a box to stallholders:
- Profit from a sale to greengrocers:
- Profit from a sale to stallholders:

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#### According to this example, the decision matrix is as follows:

|  | $s_0$ | <i>S</i> <sub>1</sub> | <i>S</i> <sub>2</sub> | <i>s</i> <sub>3</sub> | <i>S</i> <sub>4</sub> |
|--|-------|-----------------------|-----------------------|-----------------------|-----------------------|
| $a_0$  |       |                       |                       |                       |                       |
| a <sub>1</sub>   |       |                       |                       |                       |                       |
| a <sub>0</sub><br>a <sub>1</sub><br>a <sub>2</sub><br>a <sub>3</sub><br>a <sub>4</sub> |       |                       |                       |                       |                       |
| <i>a</i> 3   |       |                       |                       |                       |                       |
| $a_4$  |       |                       |                       |                       |                       |

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## **Decision Making Under Certainty**

- Every parameter of the decision problem is certain.
- The Linear Programming (LP) models (include in MTM3691) are conventional examples of decision making under certainty.
- Also, Analytic Hierarchy Process (AHP) which is designed for prioritizing the alternatives is an example of decision making under certainty.

Payoff Matrix Under Certainty:

|       | S   | • If $v(a_i, s)$ is a gain (profit), the objective will be |
|-------|---|--|
| $a_1$ | <i>v</i> ( <i>a</i> <sub>1</sub> , <i>s</i> ) | (  |
| $a_2$ | $v(a_1,s) \ v(a_2,s)$                         | $\max_{a_i} v(a_i, s),$                                    |
| :     | :   | ai   |
|       | ·   |  |
| ai    | :<br>v( <i>a</i> <sub>i</sub> , s)            | • If $v(a_i, s)$ is a loss (cost), the objective will be   |
| -     | :<br><i>v(a<sub>m</sub>,s</i> )               |  |
| a     | $v(a_m,s)$                                    | $\min_{a_i} v(a_i, s)$                                     |
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#### Example

A wholesaler is considering to order apples at the beginning of the week. Apples are bought in 100 kg boxes and sold to greengrocers. The purchasing price of apples is 6 TL/kg, and the selling price to greengrocers is 10 TL/kg. At the end of the week, the wholesaler transfers the remaining apples to marketers at a price of 4 TL/kg. From this wholesaler's experience from the previous weeks; he/she knows that the demand for a box of apples is **exactly** 2 boxes. How many boxes of apples should this wholesaler order?

The associated payoff matrix will be



According to this table, the optimal solution will be

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### **Decision Making Under Risk**

If the probability of the states can be determined according to a market research or from previous experiences, then the payoffs associated with each decision states can be described by probability distributions and the decisions made are called decision making under risk. First, the expected value of each action is determined:

$$\mathrm{E}(a_i) = \sum_{s_j} \mathrm{P}(s_j) v(a_i, s_j)$$

The option that gives the best expected value is optimal. In profit type decisions, the objective will be

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\max_{s_i} E(s_i),
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and, in cost type decisions, the objective will be

$$\min_{s_i} E(s_i),$$

Returning back to the wholesaler example, suppose that the greengrocer records 50 weeks of demands as follows:

| Demands         | Week  | Probabili | ty    |       |       |   |     |
|-----------------|-------|-----------|-------|-------|-------|---|-----|
| 0 box           | 5     | 0.1       |       |       |       |   |     |
| 1 box           | 10    | 0.2       |       |       |       |   |     |
| 2 box           | 20    | 0.4       |       |       |       |   |     |
| 3 box           | 10    | 0.2       |       |       |       |   |     |
| 4 box           | 5     | 0.1       |       |       |       | _ | 000 |
|                 | •     | •         | < L > | 1.5.1 | 가 큰 가 | 1 | 500 |
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# **Decision Making Under Risk**

|  | $S_0$ | <b>S</b> 1 | <b>S</b> 2 | $S_3$ | $S_4$ |   |
|--|-------|------------|------------|-------|-------|---|
|  | 0.1   | 0.2        | 0.4        | 0.2   | 0.1   | - |
| $a_0$  |       |            |            |       |       | - |
| $a_1$  |       |            |            |       |       |   |
| $a_2$  |       |            |            |       |       |   |
| a <sub>0</sub><br>a <sub>1</sub><br>a <sub>2</sub><br>a <sub>3</sub><br>a <sub>4</sub> |       |            |            |       |       |   |
| $a_4$  |       |            |            |       |       |   |

According to these demands, the expected values of the states can be calculated as follows:

$$\begin{array}{l} \mathrm{E}(a_0) = \\ \mathrm{E}(a_1) = \end{array}$$

 $E(a_2) =$ 

 $E(a_3) =$ 

 $E(a_4) =$ 

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| Accordingly, | is optimal.       |         | 2 | ୬୯୯ |
|--------------|-------------------|---------|---|-----|
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Decision Making Under Uncertainty: The Pessimistic Criterion

Based on this example, let us evaluate this decision making problem according to various decision-making criteria.

• The Pessimistic Criterion (MaxiMin/MiniMax): The decision maker is pessimistic. No matter which option he/she chooses, he/she expects the worst-case scenario to happen. Then the action that will give the best of the worst outcomes is optimal. If  $v(a_i, s_j)$  is the cost, the **minimax** criterion should be evaluated:

$$\min_{a_i} \left\{ \max_{s_j} V(a_i, s_j) \right\}$$

If  $v(a_i, s_j)$  is a gain, the **maximin** criterion should be evaluated:

$$\max_{a_i} \left\{ \min_{s_j} v(a_i, s_j) \right\}$$

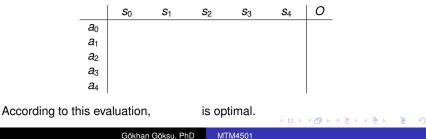
## Decision Making Under Uncertainty: The Optimistic Criterion

• Optimistic Criterion (MaxiMax/MiniMin): The decision maker is optimistic. Whichever option he/she chooses, he/she expects the event that will give the best result to happen. The option that will give the best of the best results is optimal. If  $v(a_i, s_j)$  is a cost, the **minimin** criterion should be evaluated:

$$\min_{a_i} \left\{ \min_{s_j} v(a_i, s_j) \right\}$$

If  $v(a_i, s_j)$  is the gain, the **maximax** criterion should be evaluated:

$$\max_{a_i} \left\{ \max_{s_j} v(a_i, s_j) \right\}$$



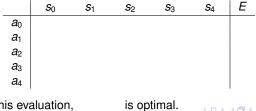
# Decision Making Under Uncertainty: Equiprobability Criterion

• Equiprobability (Laplace) Criterion: The decision maker expects the states to occur with equal probabilities. The action that will give the best expected value is optimal. If  $v(a_i, s_i)$  is a cost, the objective should be

$$\min_{a_i}\left\{\sum_{j=1}^n P(s_j)v(a_i,s_j)\right\} = \min_{a_i}\left\{\frac{1}{n}\sum_{j=1}^n v(a_i,s_j)\right\}$$

If  $v(a_i, s_j)$  is a gain, the objective should be

$$\max_{a_i} \left\{ \sum_{j=1}^n P(s_j) v(a_i, s_j) \right\} = \max_{a_i} \left\{ \frac{1}{n} \sum_{j=1}^n v(a_i, s_j) \right\}$$



According to this evaluation,

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### Decision Making Under Uncertainty: Hurwicz Criterion

• Hurwicz Criterion: The decision maker defines  $\alpha \in (0, 1)$  optimism coefficient and  $(1 - \alpha)$  pessimism coefficient. If  $v(a_i, s_i)$  is a cost, the objective should be

$$\min_{a_i} \left\{ \alpha \min_{s_j} v(a_i, s_j) + (1 - \alpha) \max_{s_j} v(a_i, s_j) \right\}$$

If  $v(a_i, s_i)$  is a gain, the objective should be

$$\max_{a_i} \left\{ \alpha \max_{s_j} v(a_i, s_j) + (1 - \alpha) \min_{s_j} v(a_i, s_j) \right\}$$

|       | $s_0$ | <b>S</b> 1 | <b>S</b> <sub>2</sub> | <b>S</b> 3 | <b>S</b> 4 | $H(\alpha = 0.7)$ |
|-------|-------|------------|-----------------------|------------|------------|-------------------|
| $a_0$ |       |            |                       |            |            |                   |
| $a_1$ |       |            |                       |            |            |                   |
| $a_2$ |       |            |                       |            |            |                   |
| $a_3$ |       |            |                       |            |            |                   |
| $a_4$ |       |            |                       |            |            |                   |

According to the degree of optimism  $\alpha = 0.7$ , the action is optimal.

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# Decision Making Under Uncertainty: Savage Regret Criterion

 Savage Regret Criterion: Rather than cost/profit values in the decision matrix, the new regret values for the regret matrix are defined:

$$p(a_i, s_j) = \begin{cases} v(a_i, s_j) - \min_{a_k} v(a_k, s_j), & \text{if } v(a_i, s_j) \text{ is a cost,} \\ \max_{a_k} v(a_k, s_j) - v(a_i, s_j), & \text{if } v(a_i, s_j) \text{ is a profit,} \end{cases}$$

$$\boxed{\begin{array}{c|c} s_0 & s_1 & s_2 & s_3 & s_4 \\\hline a_0 \\ a_1 \\ a_2 \\ a_3 \\ a_4 \\ \end{array}}$$

According to this decision matrix, the regret matrix can be created as follows:

|  | <b>S</b> 0 | <b>S</b> 1 | <b>S</b> 2 | <b>S</b> 3 | $S_4$ | S |
|--|------------|------------|------------|------------|-------|---|
| $a_0$  |            |            |            |            |       |   |
| a <sub>0</sub><br>a <sub>1</sub><br>a <sub>2</sub><br>a <sub>3</sub><br>a <sub>4</sub> |            |            |            |            |       |   |
| $a_2$  |            |            |            |            |       |   |
| $a_3$  |            |            |            |            |       |   |
| $a_4$  |            |            |            |            |       |   |

Since the regret matrix is always a cost type matrix, the pessimism criterion should be applied. Accordingly, is optimal.