MTM5135-Nonlinear Dynamical Systems

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Week 14



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MTM5135

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Cascade Interconnected iISS TDS



Consider two nonlinear TDS in cascade:

$$\begin{split} \Sigma_{1\delta} &: \quad \dot{x}_1(t) = f_1(x_{1t}, x_2(t - \delta_1)) \\ \Sigma_{2\delta} &: \quad \dot{x}_2(t) = f_2(x_{2t}, u(t)) \end{split}$$

 $\rightarrow \delta_1 \in [0, \delta]$: Interconnection through discrete delay. Questions:

- ISS preserved under cascade interconnected TDS?
- If not, conditions to ensure iISS?
- Conditions to ensure 0-GAS and UBEBS?

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Cascade Interconnected iISS TDS: Results in Delay-Free Context



Consider two nonlinear systems in cascade:

$$\begin{aligned} \Sigma_1 &: & \dot{x}_1 = f_1(x_1, x_2) \\ \Sigma_2 &: & \dot{x}_2 = f_2(x_2, u) \end{aligned}$$

- ISS is naturally preserved in cascade [Sontag, EJC, 1995]
- iISS is not preserved by cascade [Panteley, Loría, Automatica, 2001] & [Arcak et al., SICON, 2002].

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Questions:

- iISS preserved under cascade interconnected TDS?
- If not, conditions to ensure iISS?
- Conditions to ensure 0-GAS and UBEBS?

Cascade Interconnected iISS TDS: Results in Delay-Free Context

Theorem [Chaillet, Angeli, SCL, 2008]

Let V_1 and V_2 be two Lyapunov functional candidates. Assume that there exist $\gamma_1, \gamma_2 \in \mathcal{K}$, and $\alpha_1, \alpha_2 \in \mathcal{PD}$ such that, for all $(x_1, x_2) \in \mathbb{R}^{n_1} \times \mathbb{R}^{n_2}$ and all $u \in \mathbb{R}^m$,

$$\frac{\partial V_1}{\partial x_1} f_1(x_1, x_2) \leq -\alpha_1(|x_1|) + \gamma_1(|x_2|) \frac{\partial V_2}{\partial x_2} f_2(x_2, u) \leq -\alpha_2(|x_2|) + \gamma_2(|u|).$$

If $\gamma_1(s) = \mathcal{O}_{s \to 0^+}(\alpha_2(s))$, then the cascade is iISS.

 $\rightarrow q_2(s) = \mathcal{O}_{s \rightarrow 0^+}(q_1(s))$: Given $q_1, q_2 \in \mathcal{PD}$, we say that q_1 has greater growth than q_2 around zero if $\exists k \ge 0$ such that $\limsup_{s \rightarrow 0^+} q_2(s)/q_1(s) \le k$.

Questions:

- If not, conditions to ensure iISS?
- Conditions to ensure 0-GAS and BEBS?

Above condition valid for TDS?

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Theorem [G, Chaillet, Automatica, 2022]

Assume that \exists two LKF candidates $V_i : C^{n_i} \to \mathbb{R}_{\geq 0}$, $\sigma_i \in \mathcal{KL}$ and $\gamma_i \in \mathcal{K}_{\infty}$, $i \in \{1, 2\}$, such that, $\forall \phi \in C^{n_1}$, $v_1 \in \mathbb{R}^{n_2}$

$$D^{+}V_{1}(\phi, v_{1}) \leq -\sigma_{1}(|\phi(0)|, \|\phi\|) + \gamma_{1}(|v_{1}|), \tag{D1}$$

and, $\forall \varphi \in \mathcal{C}^{n_2}, v \in \mathbb{R}^m$

$$D^{+}V_{2}(\varphi, v) \leq -\sigma_{2}(|\varphi(0)|, \|\varphi\|) + \gamma_{2}(|v|)$$
(D2)

for all $t \ge 0$. Assume further that the following holds:

$$\gamma_1(s) = \mathcal{O}_{s \to 0^+}(\sigma_2(s, 0)). \tag{GR}$$

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Then, the cascade is iISS.

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Lemma [G, Chaillet, Automatica, 2022] Let $V : C^n \to \mathbb{R}_{\geq 0}$ be a LKF candidate satisfying, for all $\phi \in C^n$,

 $D^+V(\phi) \leq -\sigma(|\phi(0)|, \|\phi\|),$

for some $\alpha \in \mathcal{PD}$ and $\eta \in \mathcal{K}_{\infty}$. Let $\tilde{\alpha} \in \mathcal{PD}$ satisfying

 $\tilde{\alpha}(s) = \mathcal{O}_{s \to 0^+}(\sigma(s, 0)).$

Then, \exists a continuously differentiable function $\rho \in \mathcal{K}_{\infty}$ such that the functional $\tilde{V} := \rho \circ V$ satisfies

 $D^+ \tilde{V}(\phi) \leq -\tilde{\alpha}(|\phi(0)|).$

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- Proof can be made applying chain rule to $\tilde{V} := \rho \circ V$.
- Result in finite-dimension: [Sontag, Teel, TAC, 1995]

Proof of Theorem (Sketch). Proof of Forward Completeness.

• (D2) implies forward completeness of $\dot{x}_2(t) = f_2(x_{2t}, u(t))$.

▶ (D1) with $u_1(t) = x_2(t - \delta_1) \Rightarrow \nexists$ any finite escape time for $x_1(t)$.

Proof of 0-GAS (Sketch).

Consider the input-free system

$$\dot{x}_1(t) = f_1(x_{1t}, x_2(t - \delta_1)),$$

$$\dot{x}_2(t) = f_2(x_{2t}, 0).$$

$$\blacktriangleright \text{ (GR)+Lemma} \Rightarrow \exists \rho \in \mathcal{K}_{\infty} \cap \mathcal{C}^1 \text{ such that } \tilde{V}_2 := \rho \circ V_2 \text{ satisfies}$$

$$D^+ \tilde{V}_2(x_{2t}) < -2\gamma_1(|x_2(t)|). \tag{1}$$

$$D^{*}V_{2}(X_{2t}) \leq -2\gamma_{1}(|X_{2}(t)|).$$

Now, consider the LKF defined as

$$\mathcal{V}_2(\phi_2) := ilde{V}_2(\phi_2) + \int_{-\delta_1}^0 \gamma_1(|\phi_2(\tau)|) d au, \quad orall \phi_2 \in \mathcal{C}^{n_2}.$$

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Proof of Theorem (Continued). Proof of Theorem: 0-GAS (Sketch-Continued).

In view of (1), its Dini derivative therefore reads

$$D^{+}\mathcal{V}_{2}(x_{2t}) \leq -\gamma_{1}(|x_{2}(t)|) - \gamma_{1}(|x_{2}(t-\delta_{1})|).$$
(2)

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Furthermore (D1) ensures that

$$D^+V_1(x_{1t},x_2(t-\delta_1)) \leq -\frac{\alpha_1(|x_1(t)|)}{1+\eta_1(V_1(x_{1t}))} + \gamma_1(|x_2(t-\delta_1)|).$$

Summing this with (2), we get that

$$D^+\mathcal{V}(x_t) \leq -\frac{\alpha_1(|x_1(t)|) + \gamma_1(|x_2(t)|)}{1 + \eta_1(\mathcal{V}(x_t))},$$

Replacement of the solution:

- Point-wise replacement: $\phi(0) \rightarrow x(t)$
- Point-wise replacement: $\phi(-\delta) \rightarrow x(t-\delta)$
- History-wise replacement: $\phi \rightarrow x_t$

Proof of Theorem (Continued). Proof of UBEBS (Sketch).

- ► (D1)+"Fact" [Angeli et. al., IEEE TAC, 2000] $\Rightarrow \exists \alpha_1 \in \mathcal{K}, \eta_1 \in \mathcal{K}_{\infty}$ such that, $D^+ V_1(\phi, v_1) \leq -\frac{\alpha_1(|\phi(0)|)}{1 + n_1(V_1(\phi))} + \gamma_1(|v_1|),$ (D1')
- ► (D2)+"Fact" [Angeli et. al., IEEE TAC, 2000] ⇒ $\exists \alpha_2 \in \mathcal{K}, \eta_2 \in \mathcal{K}_{\infty}$ such that, $D^+ V_2(\varphi, v_1) \leq -\frac{\alpha_2(|\varphi(0)|)}{1 + \eta_2(V_2(\varphi))} + \gamma_2(|v|), \quad (D2')$
- ▶ (GR)+"Fact" [Angeli et. al., IEEE TAC, 2000] $\Rightarrow \exists k \geq 0$ such that $\alpha_2(s) \geq k\gamma_1(s), \forall s \in [0, 1].$
- ► Define $\tilde{\eta}_2(s) := s + \eta_2(s) + \frac{k}{\alpha_2(1)} \gamma_1 \circ \underline{\alpha}_2^{-1}(s)(1 + \eta_2(s))$, we obtain $\frac{\alpha_2(|\varphi(0)|)}{1 + \eta_2(V_2(\varphi))} \ge k \frac{\gamma_1(|\varphi(0)||)}{1 + \tilde{\eta}_2(V_2(\varphi))}, \quad \forall \varphi \in \mathcal{C}^{n_2}.$
- ► Integrating (D1') along the solution of the driving subsystem $\int_{0}^{t} \gamma_{1}(|x_{2}(\tau)|) d\tau \leq \xi_{1}(||x_{10}||) + \xi_{2}\left(\int_{0}^{t} \gamma_{2}(|u(\tau)|) d\tau\right)$

for some $\xi_1, \xi_2 \in \mathcal{K}_{\infty}$ which plays the key role to get UBEBS with c = 0.

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∴ 0-GAS + UBEBS with $c = 0 \Rightarrow$ iISS.

Cascade Interconnected iISS TDS: A Corollary for GAS

Consider the following input-free cascade:

$$\dot{x}_1(t) = f_1(x_{1t}, x_2(t - \delta_1))$$

 $\dot{x}_2(t) = f_2(x_{2t})$

Corollary [G, Chaillet, Automatica, 2022]

Assume that \exists two LKF candidates $V_1 : \mathcal{C}^{n_1} \to \mathbb{R}_{\geq 0}$ and $V_2 : \mathcal{C}^{n_2} \to \mathbb{R}_{\geq 0}$, $\sigma_1, \sigma_2 \in \mathcal{KL}$ and $\gamma_1 \in \mathcal{K}_{\infty}$ such that, $\forall \phi \in \mathcal{C}^{n_1}, v_1 \in \mathbb{R}^{n_2}$

$$D^+V_1(\phi, v_1) \leq -\sigma_1(|\phi(0)|, \|\phi\|) + \gamma_1(|v_1|),$$

and, $\forall \varphi \in \mathcal{C}^{n_2}$,

 $D^+V_2(\varphi) \leq -\sigma_2(|\phi(0)|, \|\phi\|).$

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Assume also that $\gamma_1(s) = \mathcal{O}_{s \to 0^+}(\sigma_2(s, 0))$. Then, the cascade is GAS.

Cascade Interconnected iISS TDS: Illustrative Examples

Example

Consider the following cascade TDS:

$$\dot{x}_1(t) = -\operatorname{sat}(x_1(t)) + \frac{1}{4}\operatorname{sat}(x_1(t-1)) + x_1(t)x_2(t-2)^2$$
 (C1a)

$$\dot{x}_2(t) = -\frac{3}{2}x_2(t) + x_2(t-1) + u(t)\int_{t-1}^t x_2(\tau)d\tau.$$
 (C1b)

•
$$\operatorname{sat}(s) := \operatorname{sign}(s) \min\{|s|, 1\}$$
 for all $s \in \mathbb{R}$.

•
$$n_1 = n_2 = 1, m = 1, \delta_1 = \delta = 2.$$

Consider the LKF candidates defined as

$$V_{1}(\phi_{1}) := \ln \left(1 + \phi_{1}(0)^{2} + \frac{1}{2} \int_{-1}^{0} \phi_{1}(\tau) \operatorname{sat}(\phi_{1}(\tau)) d\tau \right),$$

$$V_{2}(\phi_{2}) := \ln \left(1 + \phi_{2}(0)^{2} + \int_{-1}^{0} \phi_{2}(\tau)^{2} d\tau \right),$$

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Cascade Interconnected iISS TDS: Illustrative Examples

By deriving, we have

$$\begin{aligned} D^{+}V_{1}(x_{1t}, x_{2t}) &\leq -\frac{x_{1}(t)\mathrm{sat}(x_{1}(t))}{1 + \eta_{1}(\|x_{1t}\|)} + 2x_{2}(t-2)^{2} \\ D^{+}V_{2}(x_{2t}, u(t)) &\leq -\frac{x_{2}(t)^{2}}{1 + \eta_{2}(\|x_{2t}\|)} + |u(t)|. \end{aligned}$$

where $\eta_i(s) = e^{\overline{\alpha}_i(s)} - 1$, i = 1, 2. The functions are

- $\triangleright \ \alpha_1(s) = \operatorname{sat}(s)s,$
- $\triangleright \ \alpha_2(s) = s^2,$

•
$$\gamma_1(s) = 2s^2$$
 and

$$\triangleright \ \gamma_2(s) = s.$$

- \rightarrow Growth-rate condition: $2s^2 = \mathcal{O}_{s \rightarrow 0^+}(s^2)$.
- ... Thus, the cascade (C1) is iISS.

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Cascade Interconnected iISS TDS: Illustrative Examples Example

Consider the bilinear TDS in cascade with a discrete-delayed driven and a distributed-delayed driving subsystems

$$\dot{x}(t) = A_1 x(t) + \left(\sum_{i=1}^{n_2} z_i(t) A_{1,i}\right) x(t-\delta) + B_1 z(t),$$
 (C2a)

$$\dot{z}(t) = A_2 z(t) + \left(\sum_{i=1}^m u_i(t) A_{2,i}\right) \int_{-\delta}^0 z(t+s) ds + B_2 u(t).$$
(C2b)

- ► A₁ and A₂ are Hurwitz matrices.
- All matrices have appropriate dimensions.
- We know from [Pepe, Jiang, SCL, 2006] that (C2a) and (C2b) are iISS but not ISS.

We consider the LKF candidates, for all $\phi \in C^{n_1}$ and $\varphi \in C^{n_2}$, as

$$\begin{split} V_1(\phi) &= \ln\left(1 + \phi^\top(0) P_1 \phi(0) + p_2 \int_{-\delta}^0 |\phi(s)|^2 ds\right), \\ V_2(\varphi) &= \ln\left(1 + \varphi^\top(0) R_1 \varphi(0) + r_2 \int_{-\delta}^0 \int_{s_1}^0 |\varphi(s_2)|^2 ds_2 ds_1\right). \end{split}$$

where P_1 and R_1 are positive definite symmetric matrices and $\dot{p_1} > 0$ and $r_1 > 0$ are scalars to be determined later.

Cascade Interconnected iISS TDS: Illustrative Examples

Example

Consider the bilinear TDS in cascade with a discrete-delayed driven and a distributed-delayed driving subsystems

$$\dot{x}(t) = A_1 x(t) + \left(\sum_{i=1}^{n_2} z_i(t) A_{1,i}\right) x(t-\delta) + B_1 z(t),$$
(C2a)

$$\dot{z}(t) = A_2 z(t) + \left(\sum_{i=1}^m u_i(t) A_{2,i}\right) \int_{-\delta}^0 z(t+s) ds + B_2 u(t).$$
(C2b)

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The derivative of the LKFs along the lines of the subsystems reads

$$D^{+}V_{1}(x_{t}, z(t)) \leq -\frac{|x(t)|^{2}}{1 + \eta_{1}(||x_{t}||)} + \gamma_{1}|z(t)|^{2}$$
$$D^{+}V_{2}(z_{t}, u(t)) \leq -\frac{|z(t)|^{2}}{1 + \eta_{2}(||z_{t}||)} + \gamma_{2}|u(t)|^{2}$$

for $\eta_i(s) = e^{\overline{\alpha}_i(s)} - 1$, i = 1, 2 and appropriately chosen $\gamma_1, \gamma_2 > 0$.

... GR condition is also satisfied. Thus, the cascade (C2) is iISS.

Conclusions and Perspectives

Overview:

- Several I K characterizations of iISS for TDS.
- \mathcal{KL} dissipation rates simplify the iISS analysis.
- The existing theory for input/disturbance-free systems is also relaxed.
- Robustness Property: 0-GAS+UBEBS⇔iISS.
- Conditions under which the cascade of two iISS TDS is iISS.
- Growth restrictions on the input rate of the driven subsystem and the dissipation rate of the driving one.

Open Questions:

- Converse theorem for iISS LKF with point-wise dissipation.
- Characterizations for ISS TDS.
- Converse theorem for Strong iISS in finite-dimensional context.
- Solns based characterizations for iISS TDS.
- Conditions to ensure strong iISS for TDS.
- C-ISS-TDS

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For further open questions see [Chaillet, Karafyllis, Pepe, Wang, MCSS, 2022, Chapter 8].